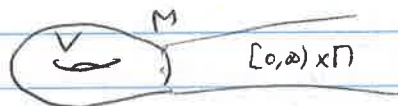


# Momchil - Symplectic homology

Goal: if  $W, W'$  are two subcritical Stein fillings of  $(M, \xi)$  with  $c_1(W) = c_1(W') = 0$ , then  $H^*(W) \cong H^*(W')$ .

$(V, \lambda)$ ,  $d\lambda$  is symplectic,  $Z$  str  $i_Z d\lambda = \lambda$ , and  $Z$  is positively transverse to  $\partial V \Rightarrow \alpha := \lambda|_{\partial V}$  is contact. Then,  $(\hat{V}, \hat{\lambda})$  is the completion  $(V, \lambda) \cup_{\partial V} ([0, \infty) \times M, e^r \alpha)$ .



Pick  $H: \hat{V} \rightarrow \mathbb{R}$  and define

$$A^H: C^\infty(\mathbb{R}/\mathbb{Z}, \hat{V}) \rightarrow \mathbb{R}: x \mapsto \int_{S^1} x^* \hat{\lambda} - \int_{S^1} H(x(t)) dt.$$

Then,  $dA^H_x = \int_{S^1} d\lambda(\xi(t), \dot{x}(t) - x^H(x(t))) dt$ ; for  $x$  to be a critical point, need  $\dot{x}(t) = x^H(x(t))$ .

$\Rightarrow$  crit. points are orbits of  $H$ .

Want to do Morse theory. To get a metric on  $C^\infty(S^1, \hat{V})$ , put one on  $\hat{V}$  first: pick  $J: T\hat{V} \rightarrow T\hat{V}$ ,  $J^2 = -1$ ,  $d\lambda(-, J-)$  is a Riemannian metric. For this,  $D_x A^H = -J(\dot{x} - x^H(x))$ .

The upward gradient flow is: for a path  $u: \mathbb{R}_+ \times S^1 \rightarrow \hat{V}$ , have  $\partial_s u + J(\partial_t u - x^H) = 0$ . "Floer's equation"

$\leadsto$  "Just do Morse theory": let  $CF_k(H) := \bigoplus_{x \in \text{crit}(A^H)} \mathbb{F}_2 \cdot x$

For  $c_1(V) = 0$ ,  $CZ(x) \in \mathbb{Z}$ ; define  $|x| = CZ(x) + n - 3$ . Define a differential by  $d: CF_k(H) \rightarrow CF_{k-1}(H)$ :

$$d(x_+) = \sum_{\substack{x \in \text{crit}(A^H) \\ |x_-| = |x_+| - 1}} \#_{\mathbb{F}_2} M(x_-, x_+) x_-$$

$$\left\{ \begin{array}{l} u: \partial_s u + J(\partial_t u - x^H) = 0 \\ \lim_{s \rightarrow \infty} u(s, t) = x_-(t) \end{array} \right\} / \mathbb{R} \quad \text{R-translation}$$

For these indices, that is 0-dimensional, but we don't know whether it's finite.

Compactness: Gromov compactness works if the following holds:

(a) uniform  $C^0$  bounds

(b) uniform energy bounds.

$$\hookrightarrow E(u) = A^H(x_+) - A^H(x_-)$$

$\Rightarrow d$  decreases action.

(b) comes for free, as  $A^H(x_+)$  and  $A^H(x_-)$  are fixed.

(a) needs some serious restrictions.



write  $h(t) = At + B$

**Definition:** the spectrum  $\text{Spec}(\Omega, \alpha) = \{T \in \mathbb{R} \mid \exists \text{Reeb orbit of } \alpha \text{ with period } T\}$ .

**Definition:** the space of admissible Hamiltonians is

$\text{Ad}(V, \lambda) := \{H: \hat{V} \rightarrow \mathbb{R} \mid \text{outside a compact set, } \partial_t H = H \text{ and } \text{slope}(H) \notin \text{Spec}(\Omega, \alpha)\}$

**Rem. 2:**  $\mathbb{S}^1$ , so this means  $H: \hat{V} \rightarrow \mathbb{R}$  looks like  $H(r, y) = Ae^r + b$  in the cylindrical end, and  $A \notin \text{Spec}(\Omega, \alpha)$  is not in the slope.

**Definition:** a  $J: T\hat{V} \rightarrow T\hat{V}$  is called cylindrical if on the cylindrical end,  $J = j \oplus J_{\mathbb{E}}$ , st  $j_{\mathbb{S}^1} = R$  and  $J_{\mathbb{E}}: \mathbb{E} \rightarrow \mathbb{E}$  is a  $\mathbb{C}$ -str. on  $\mathbb{E}$ .

These choices ensures  $C^0$  bounds  $\Rightarrow$  compactness  $\Rightarrow d$  is well-defined and  $d^2 = 0$ .

**Definition:**  $\text{HF}_k(H) := H_k(\text{CF}_*(H), d)$

**Rem:** a priori this should depend on  $J$ , but in fact, it does not.

In the cylindrical end, if  $u(s, t) = (a(s, t), v(s, t))$ , the equation is  $\Delta a + \partial_s(h'(e^a)) = \|\partial_s v\|^2 \geq 0$ , so by maximum principle, we can't have max in interior.  $\int \Delta a \leq 0$  because max if there is one, have  $\partial_s(h'(e^a)) = h''(e^a)e^a \partial_s a \neq 0$  because max, hence contradiction (or almost, since the whole thing could be  $= 0$ ).

Independence of  $H$ ?

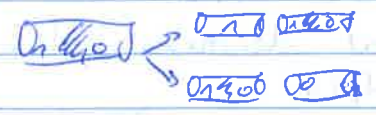
$H_+, H_- \in \text{Ad}(V, \lambda)$ . Let  $H_s: \hat{V} \rightarrow \mathbb{R}$  path from  $H_-$  to  $H_+$ , and interpolate by considering solutions to the equation

$\partial_s u + J(\partial_t u - X^{H_s}(u)) = 0$

$H_0 \ll 0$        $H_{s \gg 0}$   
"                      "

$\Delta$  no  $\mathbb{R}$ -translation.

Define  $\Phi: \text{CF}(H_+) \rightarrow \text{CF}(H_-)$ ,  $\Phi(x_+) = \sum_{x_- \in \text{crit}(H_-)} \# \mathcal{M}(x_+, x_-) x_-$

Possible breakings:  so it's a chain map

For compactness, we get the equation  $\Delta a + \partial_s(h'_s(e^a)) = \|\partial_s v\|^2 \geq 0$ , but there is a  $\partial_s(h'_s)(e^a)$  is there, that might ruin the previous argument. However, it's fine if  $\partial_s h'_s < 0$ , i.e. if  $H_-$  has steeper slope than  $H_+$ .

So get only a map in one direction.

$\Rightarrow$  Define a partial order on  $\text{Ad}(V, \lambda)$ : we say  $H_1 \ll H_2$  if  $H_1 < H_2$  outside a compact set (ie  $\neq$  slopes, or one is shift of the other)



Also, by a homotopy of homotopies argument,  
 $HF(H_1) \rightarrow HF(H_2) \rightarrow HF(H_3)$  commutes.

Also, this forms a directed system:  $HF(H) \rightarrow HF(\tilde{H})$

**Definition:**  $SH_k(V) = \varinjlim_{H \in \mathcal{A}(V, \lambda)} HF_k(V)$ , can compute it using a cofinal sequence.

What are the generators? Take a cofinal sequence of Hamiltonians looking like this, with increasing slope in the cylindrical end.



**Fact 1:** if  $H$  is  $C^2$ -small ( $\|H_{\text{less}} H\| \ll \epsilon$ ), then all the 1-periodic orbits of  $X^H$  are constant, i.e. crit pts of  $H$ . Moreover, the Floer trajectories connecting crit pts of  $H$  are just Reeb flow lines.

Compute:  $X^H = h'(e^\theta) R$ , so orbits lie in constant  $r_\theta$  level, and they coincide with Reeb orbits, up to reparametrization, of period  $h'(e^\theta) = T$ , and has action  $A^H(x) = e^\theta \cdot T - h(e^\theta) \geq T \cdot h(e^\theta) > 0$ .

There is ~~no~~  $CF^{low}$  So, due to the hypothesis on slope & spectrum, we see that there are no Reeb orbits in the linear part.

Also, there is  $0 \rightarrow CF^{low}(H) \rightarrow CF(H) \rightarrow CF(H) \rightarrow 0$ , because the differential decreases action. So, get exact triangle

$$SH^{low}(V) \leftarrow H^{-k}(V) \rightarrow SH_k(V) \leftarrow SH_k(V) \quad \text{[Bourgeois-Dancnea]}$$

**Theorem:** if all Reeb orbits of  $(\Pi, \kappa)$  satisfy  $C\mathcal{R}(r) + n - 3 > 0$  and  $v, w$  are 2 exact fillings of  $\Pi$  with  $c_1(v) = c_1(w) = 0$ , then  $SH^+(v) \cong SH^+(w)$ . So, it's an invariant of the compact manifold.

**Proof:** we show no cylinder goes into the filling. Stretch the neck: if we have a seq. of cylinders going in the filling, stretch the neck  $\Rightarrow$  it has to break in  $S^2$  or  $\mathbb{C}P^1$ , ruled out by index: it will be negative.  $D$



with  $c_1(\text{filling}) = 0$ 

Theorem (M-L Yau) if  $M$  is subcritically Stein fillable, then  $M$  admits a contact form st  $CZ(\gamma) + n - 3 > 0 \forall$  Reeb orbit  $\gamma$ .

Theorem (Cieliebak)  $\forall$  subcritical Stein with  $c_1(V) = 0 \Rightarrow SH(V) = 0$ .

So, we can prove the goal:  $SH(V) = SH(W) = 0$ , and  $SH^+(V) = SH^+(W)$ , so by the exact triangle above, we have  $H^+(V) = H^+(W)$ . The index assumption on Reeb orbits is satisfied by Yau's theorem.

Rem: Floor cylinders have to approach the negative orbit "by the right a little bit":  $\exists (s_0, t_0) \in \mathbb{R} \times S^1$  st  $a(s_0, t_0) > r_-$ , where  $r_-$  is the  $r$ -level of the negative Reeb orbit.

This is due to Bourgeois-Caneva, and helps to rule out  $\mathbb{C}P^2$  above: must have  $\infty$  for the bottom right one, but that contradicts the maximum principle.

One should remember this as one of the fundamental properties of holomorphic curves, along with the maximum principle. (Kyler)